

# CANopen Interface for the GE Fanuc Series 90<sup>™</sup>-30 PLC Product Specifications and Installation Data

# 1 DESCRIPTION

The Horner APG CANopen Interface Module (HE693CAL101) allows Cegelec and Lenze drives to be directly connected to the GE Fanuc Series 90<sup>™</sup>-30 PLC. These drives feature built-in CAN communications, supporting the industry standard CANopen protocol. Performance of the CANopen interface is far superior to serial protocols typically supported by other drives. It is also cost effective, as the CAN interface is designed into the drives without the requirement of a communications option board. The CANopen module (CAL101) resides in any slot of the Series 90-30 PLC. Any of the Series 90-30 PLCs, from the CPU311 on up, are supported by the module. Up to eight drives, addressed 1-8, can communicate with the PLC module, addressed at 32. The module is pre-configured, so no network configuration is necessary.

| Table 1 - HE693CAL101 Specifications |              |                                |                              |
|--------------------------------------|--------------|--------------------------------|------------------------------|
| Specification                        | Part Number  | Specification                  | Part Number                  |
| PLC Power<br>Consumption             | 175mA @ 5VDC | Drives Supported               | 8                            |
| Network Voltage                      | 11 to 25VDC  | PLC Data Registers<br>Required | 32 %AI and 32 %AQ            |
| Operating<br>Temperature             | 0 to 60°C    | Relative Humidity              | 5 to 95%, non-<br>condensing |

## 2 SPECIFICATIONS

### 3 CONFIGURATION

| SLOT<br>2 | Catalog <b>#:</b> FO  | EIGN   | IKE CUNF   | FOREIGN M  | ODULE   |  |
|-----------|---|--|--|--|---|--|
| FRGN      | Module ID :<br>%I Ref Adr :<br>%I Size :<br>%Q Ref Adr :<br>%Q Size :<br>%AI Ref Adr:<br>%AI Size :<br>%AQ Ref Adr:<br>%AQ Size : | ×10001<br>0<br>×Q0001<br>0<br>×A1001<br>32<br>×AQ001<br>32 | Byte 1<br>Byte 2<br>Byte 3<br>Byte 4<br>Byte 5<br>Byte 6<br>Byte 7<br>Byte 8 | : 0000000<br>: 551(5555)<br>: 02<br>: 01<br>: 00<br>: 00<br>: 00<br>: 00 | 1 Byte 9<br>3 Byte 10<br>Byte 11<br>Byte 12<br>Byte 13<br>Byte 14<br>Byte 15<br>Byte 16 | : 00<br>: 00<br>: 00<br>: 00<br>: 00<br>: 00<br>: 00 |

#### Figure 1 - Foreign Module Configuration

To reach this screen, select I/O Configuration (F1), cursor over to the slot containing the module and select Other (F8), and Foreign (F3). The sample configuration above shows the proper configuration for a CANopen module (CAL101) set for address 32 (Byte 2 = 0010000); baud rate 500KHz (Byte 3 = 02H), and Synchronization Jump Width of 1 (Byte 3 = 01H).

| Table 2 – Configuration Parameters |              |               |                                     |  |
|------------------------------------|--------------|---------------|-------------------------------------|--|
| Byte 1                             | Byte 2       | Byte 3        | Byte 4                              |  |
| Smart Module ID<br>Bit             | CAN ID       | CAN Baud Rate | Synchronization<br>Jump Width (SJW) |  |
| Always 00000001                    |              | 0 = 125KHz    |                                     |  |
|                                    | 0.32 hipppy  | 1 = 250KHz    | 1-4                                 |  |
|                                    | 0-52, binary | 2 = 500KHz    |                                     |  |
|                                    |              | 3 = 1MHz      |                                     |  |

Byte 1 is always 1, Byte 2 is the node address, Byte 3 is the baud rate, and Byte 4 is the Synchronization Jump Width. The legal values for these configuration parameters are shown in the table above.

# 4 WIRING



Figure 2 – HE693CAL101 Wiring

**NOTES:** V+ and V- are twisted pair.

CAN\_H and CAN\_L are twisted pair.

Overall Shield connected to "Shield" Terminal.

# 5 DATA MAP

| Table 3 – Data from Drive to PLC |                       |                      |  |
|----------------------------------|-----------------------|----------------------|--|
| Drive<br>Number                  | Node Address<br>(TID) | PLC Data<br>Location |  |
| 1                                | 1                     | %AI 001-004          |  |
| 2                                | 2                     | %AI 005-008          |  |
| 3                                | 3                     | %AI 009-012          |  |
| 4                                | 4                     | %AI 013-016          |  |
| 5                                | 5                     | %AI 017-020          |  |
| 6                                | 6                     | %AI 021-024          |  |
| 7                                | 7                     | %AI 025-028          |  |
| 8                                | 8                     | %AI 029-032          |  |

| Table 4 – Data from PLC to Drive |                 |                             |  |
|----------------------------------|-----------------|-----------------------------|--|
| PLC Data<br>Location             | Drive<br>Number | Drive Node<br>Address (RID) |  |
| %AI 001-004                      | 1               | 1                           |  |
| %AI 005-008                      | 2               | 2                           |  |
| %AI 009-012                      | 3               | 3                           |  |
| %AI 013-016                      | 4               | 4                           |  |
| %AI 017-020                      | 5               | 5                           |  |
| %AI 021-024                      | 6               | 6                           |  |
| %AI 025-028                      | 7               | 7                           |  |
| %AI 029-032                      | 8               | 8                           |  |

**Data Transfer**. Four words of data is read and written between the PLC and each drive. The PLC is preconfigured to communicate with up to eight drives. Data produced by the drives shows up in %AI (analog input) registers in the PLC. Data consumed by the drives are set in %AQ registers in the PLC. The two tables above show the data transferred from the Drive to the PLC (at left) and the data transferred from the PLC to the drive (at right).

# 6 TECHNICAL ASSISTANCE

For user manual updates, contact Horner APG, Technical Support Division, at (317) 916-4274 or visit our web site at www.heapg.com.