



# MICRO OCS MODEL: HE-X5

**Built-In I/O: 4 Digital DC Inputs,  
4 Digital DC Outputs, 4 Analog Inputs**

## 1 TECHNICAL SPECIFICATIONS

### 1.1 General

Required Pwr. (steady state)	270mA at 12VDC 150mA at 24VDC
Required Pwr. (inrush)	20A for < 1 ms at 24V DC Switched
Primary Pwr. Range	10-30VDC
Required Pwr with Backlight @ 50%	96mA @ 24VDC
Backlight OFF	86mA@ 24VDC
Battery	Non-removable (RTC only)
Clock Accuracy	+/- 8 seconds/month at 25°
Real Time Clock	With Battery
Battery Life	5-10 Yrs Not Replaceable
Relative Humidity	5-95% non-condensing
Operating Temp.	-10°C to +60°C
Storage Temp.	-30°C to +70°C
Altitude	Up to 2000m
Rated Pollution Degree	Evaluated for Pollution Degree 2 Rating
Weight	10 oz / 271 g
Certifications (CE)	<a href="#">North America</a> <a href="#">Europe</a>

### 1.2 Display

Display Type	Resistive 4.3" Touchscreen 450 cd/m <sup>2</sup> (nits)
Resolution	WVGA (480 x 272)
Color	65K Color
Screen Memory	22MB
User-Program. Screens	1023
Backlight	White LED

### 1.3 Connectivity

Serial	2 (1xRS232, 1x2-wire RS485)
CAN	CAN 125kbps - 1Mbps
Ethernet	1 x 10Mbps/100Mbps
USB (2)	1 x Mini Program, 1 x USB Flash
microSD	1 x SD, SDHC, SDXC in FAT32 format

### 1.4 Digital DC Inputs

Inputs per Module	4	
Commons per Module	1	
Input Voltage Range	0VDC - 24VDC	
Absolute Max. Voltage	30VDC Max.	
Input Impedance	10kΩ	
Input Current	Pos. Logic	Neg. Logic
Min. "On" Current	0.8mA	-1.6mA
Max. "Off" Current	0.3mA	-2.1mA
Min. "On" Input	8VDC	
Max. "Off" Input	3VDC	
OFF to ON Response	2ms min*	
ON to OFF Response	2ms min*	
Galvanic Isolation	None	
Logic Polarity	Pos. or Neg. Based on configuration	
I/O Indication	None	
High Speed Counter (HSC)	4 HSC	
HSC Max. Frequency	500kHz Max.	
Connector Type	3.5mm Pluggable Cage Clamp	

### 1.5 Analog Inputs

Number of Channels	4	
Input Signal Range	4-20mA, 0-20mA DC, 0-10VDC	
Input Raw Value Range	0-32,000	
Abs. Max. Input Voltage	-0.5 to 12VDC	
Galvanic Isolation	None	
Input Impedance (clamped at -0.5 to 12 Vdc)	mA: 50Ω	V: 500kΩ
Nominal Resolution	12 Bits	
Conversion Speed	All Channels Once Per OCS Scan	
Analog Max Error @ 25°C	1.5% of full scale	

### 1.6 Digital DC Outputs

Outputs per Module	4	
Commons per Module	1	
Output Type	Half-Bridge	
Absolute Max. Voltage	30VDC Max.	
Output Protection	Short Circuit & Overvoltage	
Max. Output Current per Point	0.5A	
Max. Total Current	2A Total Current	
Max. Output Supply	30VDC	
Min. Output Supply	10VDC	
Max. Voltage Drop at Rated Current	0.25VDC	
Min. Load	None	
I/O Indication	None	
Galvanic Isolation	None	
OFF to ON Response	500ns min*	
ON to OFF Response	500ns min*	
PWM Out	500kHz Max.	
Output Characteristics	Current Sourcing (Pos. Logic)	

### 1.7 Control & Logic

Control Lang. Support	Advanced Ladder Logic Full IEC 61131-3 Languages	
Logic Program Size & Scan Rate	1MB, Max. 0.013ms/kB	
Online Programming Changes	Supported in Advanced Ladder	
Digital Inputs	2048	
Digital Outputs	2048	
Analog Inputs	512	
Analog Outputs	512	
Gen. Purpose Registers	8192 words (1024 retentive) 4096 bits (2048 retentive)	

\* all values updated 1x per scan

## 2 CONTROLLER OVERVIEW

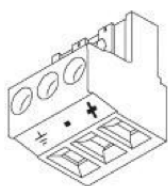
### 2.1 - Port Connectors



- |                     |                     |
|---------------------|---------------------|
| 1. Power            | 6. DIP Switches     |
| 2. Input Connector  | 7. Ethernet Port    |
| 3. Output Connector | 8. microSD Slot     |
| 4. CAN Port         | 9. USB A Port       |
| 5. Serial Ports     | 10. USB Mini B Port |

NOTE: See Precaution #12 on p.4 about USB and grounding.

### 2.2 - Power Wiring



Primary Power Port Pins		
PIN	SIGNAL	DESCRIPTION
1	Ground	Frame Ground
2	DC-	Input Power Supply Ground
3	DC+	Input Power Supply Voltage

#### DC Input / Frame

**Solid/Stranded Wire:** 12-24 awg (2.5-0.2mm).

**Strip Length:** 0.28" (7mm).

**Torque Rating:** 4.5 - 7 in-lbs (0.50 - 0.78 N-m).

DC- is internally connected to I/O V-, but is isolated from CAN V-.

A Class 2 power supply must be used.

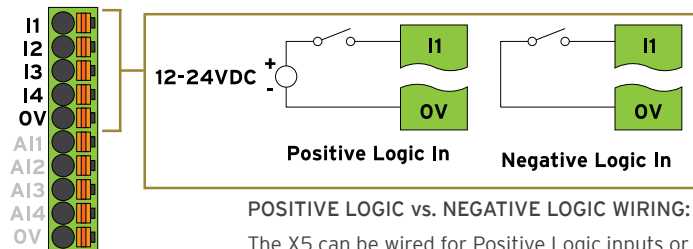
#### POWER UP

1. Attach included ferrite core with a minimum of two turns of the DC+ and DC- signals from the DC supply that is powering the controller.
2. Connect to Earth Ground
3. Apply recommended power.



## 3 WIRING: INPUTS AND OUTPUTS

### 3.1 - Digital Input Wiring



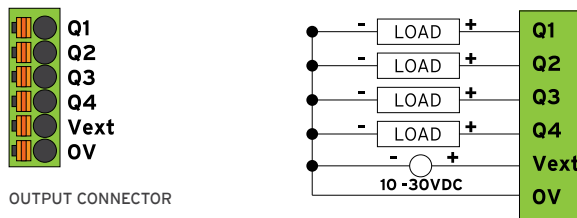
#### POSITIVE LOGIC vs. NEGATIVE LOGIC WIRING:

The X5 can be wired for Positive Logic inputs or Negative Logic inputs.

Digital inputs may be wired in either a Positive Logic or Negative Logic fashion as shown. The setting in the Cscape Hardware Configuration for the Digital Inputs must match the wiring used in order for the correct input states to be registered. No jumper settings are required for X5. When used as a normal input and not for high speed functions, the state of the input is reflected in registers %I1 - %I4.

Digital inputs may alternately be specified for use with High Speed Counter functions, also found in the Hardware Configuration for Digital Inputs. Refer to the X5 User Manual (MAN1039) for full details.

### 3.2 - Digital Output Wiring



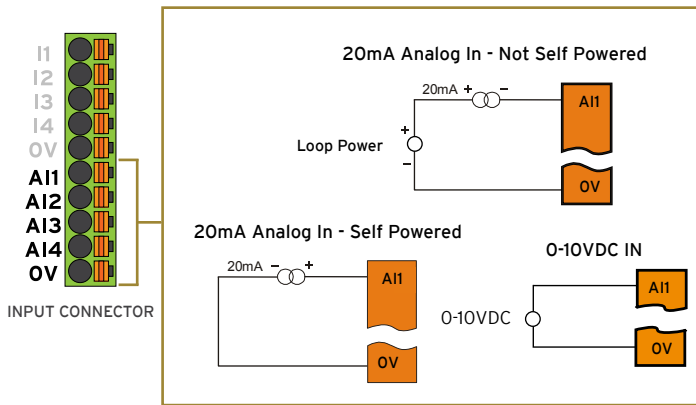
Digital outputs are Positive Logic. If an output is turned on, the voltage supplied at the Vext terminal is applied to that output. When used as normal outputs, the state of the output may be controlled using the registers %Q1, %Q2, %Q3, and %Q4.

The first two digital outputs may alternately be specified for use as Pulse Width Modulation (PWM) or Stepper outputs. The configuration for these functions is found in the Cscape Hardware Configuration for Digital Outputs. Refer to the X5 User Manual (MAN1039) for full details.

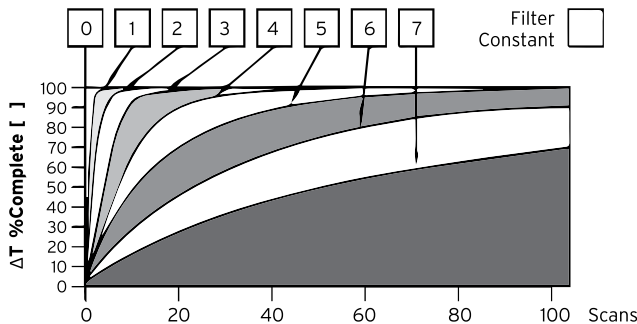
## wiring: I/O continued...

## 4 COMMUNICATIONS

### 3.3 - Analog Input Wiring



Analog inputs may be configured for 4-20mA, 0-20mA, or 0-10V ranges separately. The configuration is found in the Cscape Hardware Configuration for Analog Inputs. Wiring must match the configuration. Raw input values for channels 1-4 are found in the registers %AI1, %AI2, %AI3, and %AI4 as Integer-type data with a range from 0 - 32000. Analog inputs may be filtered digitally with the Filter Constant found in the Cscape Hardware Configuration for Analog Inputs. Valid filter values are 0 - 7 and act according to the following chart.



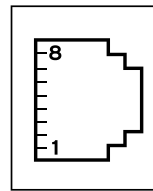
#### Data Values

INPUT MODE:	DATA FORMAT, 12-bit INT:
0-20mA, 4-20mA	0-32000

### 4.1 - CAN Communications

#### CAN Pin Assignments

PIN	SIGNAL
8	No Connection
7	Ground
6	Ground
5	No Connection
4	No Connection
3	Ground
2	CAN Data Low
1	CAN Data High



#### CAN

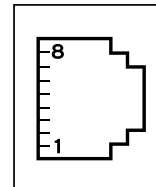
Modular jack (8posn)

**NOTE:** Refer to connector pinout on product.

The CAN port is provided via the single 8-position modular jack labeled "CAN". It may be used to communicate with other OCS products using Horner's CsCAN protocol. Additionally, remote expansion I/O such as SmartRail, SmartBlock, and SmartStix may be implemented using the CsCAN protocol.

Termination for the CAN port may be achieved by turning DIP switch 2 to the ON position. This should only occur if the X5 is at one end of the CAN daisy-chain or the other. Only the two devices on either end of the CAN daisy-chain should be terminated.

### 4.2 - Serial Communications



#### MJ1/2 SERIAL PORTS

**MJ1:** RS-232 w/full handshaking  
**MJ2:** RS-485 half-duplex  
 Two serial ports on one modular jack

PIN	MJ1 PINS		MJ2 PINS	
	SIGNAL	DIRECTION	SIGNAL	DIRECTION
8	TXD	OUT	-	-
7	RXD	IN	-	-
6	OV	GROUND	OV	GROUND
5	+5V @ 60mA	OUT	+5V @ 60mA	OUT
4	RTS	OUT	-	-
3	CTS	IN	-	-
2	-	-	RX-/TX-	IN/OUT
1	-	-	RX+/TX+	IN/OUT

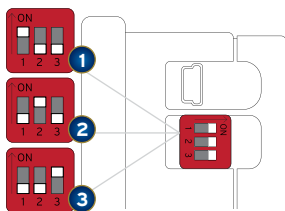
**NOTE:** Refer to connector pinout on product

Two serial ports are provided via the single 8-position modular jack labeled "MJ1/2". MJ1 defaults to one of several methods available to program the controller. It may instead be specified for RS-232 communications with or without hardware handshaking, such as for Modbus Master/Slave, or to communicate to devices such as bar code scanners.

MJ2 may only be used as half-duplex (2-wire) RS-485. The most common use is for Modbus communications, either as a Modbus Master or Modbus Slave, though many other options are also available. Termination for the RS-485 port may be achieved by turning DIP switch 1 to the ON position. Only the two devices on either end of the RS-485 daisy-chain should be terminated.

## communications continued...

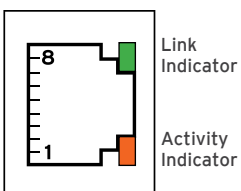
### 4.3 - Dip Switches



DIP SWITCHES				
PIN	NAME	FUNCTION	DEFAULT	
1	RS-485 Termination	ON = Terminated	OFF	
2	CAN Termination	ON = Terminated	OFF	
3	Bootload	Always Off	OFF	

The DIP switches are used to provide a build-in termination to both the MJ2 port and CAN port if needed. The termination for these ports should only be used if this device is located at either end of the multidrop/daisy-chained RS-485 network or CAN bus.

### 4.4 - Ethernet Communications



10/100 Ethernet port with automatic MDI-X (crossover detection) is provided via the single 8-position modular jack labeled "LAN". Several features are available for use over Ethernet, such as WebMI, Modbus TCP/IP, Ethernet/IP, SMTP (E-mail), and more. Ethernet configuration is done via

the Cscape Hardware Configuration, though temporary Ethernet configuration may be done through the System Menu directly on the X5. For more information on Ethernet, available features and protocols, refer to the Ethernet Supplement document (SUP0740).

### 4.5 - microSD Slot

A microSD card may be used for data and alarm logging, historic trending, program loading, firmware updates, and many other features. Supported types of microSD cards are SD, SDHC, and SDXC as long as the format of the card file system is FAT32. Card formatting may be done by the controller if no other means are available to do so.

### 4.6 - USB Ports

The USB Mini B port is provided as one of several ways to program the X5. Drivers for Windows to recognize the controller as a virtual COM port are automatically installed with Cscape software.

The USB A port is provided to be able to use a thumb drive for data and alarm logging, historic trending, firmware updates, and many other purposes. Files may also be transferred between a USB thumb drive and the installed microSD card.

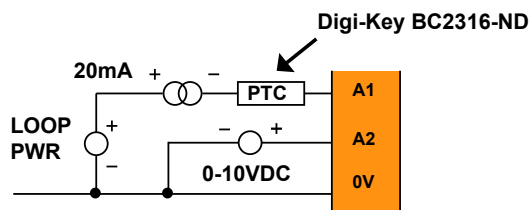
## 5 BUILT-IN I/O

### 5.1 - Register Map for X5

FIXED ADDRESS	I/O FUNCTION	X5
%I1	Digital Inputs	1-4
	Reserved	5-16
%Q1	Digital Outputs	1-4
	Reserved	5-16
%A11	Analog Inputs	1-4
	Reserved	n/a

## 6 ANALOG IN TRANZORB FAILURE

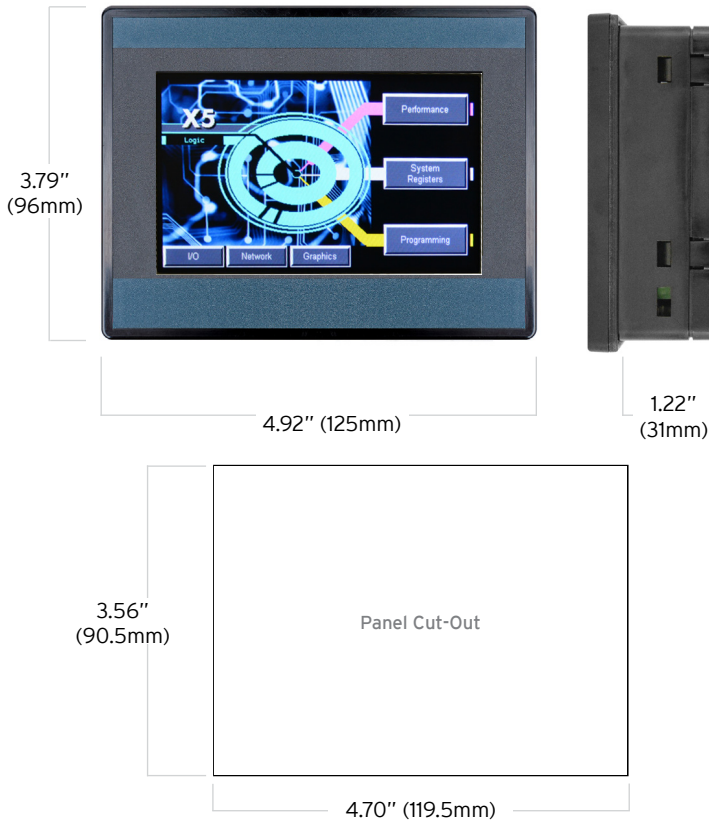
A common cause of Analog Input Tranzorb Failure on Analog Inputs: If a 4-20mA circuit is initially wired with loop power, but without a load, the analog input could see 24VDC. This is higher than the rating of the tranzorb. This can be solved by NOT connecting loop power prior to load connection, or by installing a low-cost PTC in series between the load and analog input.



## 7 INSTALLATION DIMENSIONS

## 8 SAFETY

### 7.1 - Dimensions



Panel Tolerance: +/-0.5mm

### 7.2 - Installation Instructions

The X5 utilizes a clip installation method to ensure a robust and watertight seal to the enclosure. Please follow the steps below for the proper installation and operation of the unit. This equipment is suitable for Class I, Division 2, Groups A, B, C and D or non-hazardous locations only.

1. Carefully locate an appropriate place to mount the X5. Be sure to leave enough room at the top of the unit for insertion and removal of the microSD™ card.
2. Carefully cut the host panel per the diagram, creating a 90.5mm x 119.5mm (with a tolerance of +/- 0.5mm) opening into which the X5 may be installed. If the opening is too large, water may leak into the enclosure, potentially damaging the unit. If the opening is too small, the OCS may not fit through the hole without damage.
3. Remove any burrs and or sharp edges and ensure the panel is not warped in the cutting process.
4. Install and tighten the four mounting clips (provided in the box) until the gasket forms a tight seal. For standard composite mounting clips (included with product), use a torque rating of 2-3 in-lbs (0.23-0.34 Nm). For optional metal mounting clips, use a torque rating of 4-8 in lbs (0.45-0.90 Nm).
5. Connect communications cables to the serial port, USB ports, and CAN port as required.

### 8.1 - WARNINGS

1. To avoid the risk of electric shock or burns, always connect the safety (or earth) ground before making any other connections.
2. To reduce the risk of fire, electrical shock, or physical injury, it is strongly recommended to fuse the voltage measurement inputs. Be sure to locate fuses as close to the source as possible.
3. Replace fuse with the same type and rating to provide protection against risk of fire and shock hazards.
4. In the event of repeated failure, do NOT replace the fuse again as repeated failure indicates a defective condition that will NOT clear by replacing the fuse.
5. Only qualified electrical personnel familiar with the construction and operation of this equipment and the hazards involved should install, adjust, operate, or service this equipment. Read and understand this manual and other applicable manuals in their entirety before proceeding. Failure to observe this precaution could result in severe bodily injury or loss of life.
6. **WARNING** - Battery may explode if mistreated. Do not recharge, disassemble, or dispose of in fire.
7. **WARNING - EXPLOSION HAZARD** - Batteries must only be changed in an area known to be non-hazardous.

### 8.2 - FCC COMPLIANCE

This device complies with Part 15 of the FCC Rules. Operation is subject to the following two conditions:

1. This device may not cause harmful interference
2. This device must accept any interference received, including interference that may cause undesired operation

### 8.3 - PRECAUTIONS

All applicable codes and standards need to be followed in the installation of this product. Adhere to the following safety precautions whenever any type of connection is made to the module:

1. Connect the safety (earth) ground on the power connector first before making any other connections.
2. When connecting to the electric circuits or pulse-initiating equipment, open their related breakers.
3. Do NOT make connection to live power lines.
4. Make connections to the module first; then connect to the circuit to be monitored.
5. Route power wires in a safe manner in accordance with good practice and local codes.
6. Wear proper personal protective equipment including safety glasses and insulated gloves when making connections to power circuits.
7. Ensure hands, shoes, and floor are dry before making any connection to a power line.
8. Make sure the unit is turned OFF before making connection to terminals.
9. Make sure all circuits are de-energized before making connections.
10. Before each use, inspect all cables for breaks or cracks in the insulation. Replace immediately if defective.
11. Use copper conductors in Field Wiring only, 60/75°C.
12. Use caution when connecting controllers to PCs via serial or USB. PCs, especially laptops may use "floating power supplies" that are ungrounded. This could cause a damaging voltage potential between the laptop and controller. Ensure the controller and laptop are grounded for maximum protection. Consider using a USB isolator due to voltage potential differences as a preventative measure.

## 9 BACKUP BATTERY

The X5 uses a non-replaceable, non-rechargeable 3V Lithium coin-cell battery to run the Real-Time Clock and to keep the retained register values. This battery is designed to maintain the clock and memory for 7-10 years. Please reference MAN1039 for more details about the battery.

## 10 TECHNICAL SUPPORT

For assistance and manual updates, contact Technical Support at the following locations:

### North America

(317) 916-4274  
(877) 665-5666  
[www.hornerautomation.com](http://www.hornerautomation.com)  
techsppt@heapg.com

### Europe

(+) 353-21-4321-266  
[www.hornerautomation.eu](http://www.hornerautomation.eu)  
technical.support@horner-apg.com